In the Claims:

- 1. Canceled.
- (Currently Amended) A four-wheel drive apparatus for a vehicle, comprising:

 an engine for driving a front wheel shaft of the vehicle;
 a generator connected to the engine for generating electric current;
 a motor driven by the electric current supplied from the generator; and
 a clutch interposed between the motor and a rear wheel shaft for transferring a
 driving force thereto, The four wheel drive apparatus of claim 1, further comprising:
 - a first speed sensor for detecting RPM of the front wheel shaft;
 - a second speed sensor for detecting RPM of the rear wheel shaft; and
 - a controller,

wherein the controller controls the motor based on a difference between the RPM of the front wheel shaft and that of the rear wheel shaft.

- 3. (Original) The four-wheel drive apparatus of claim 2, further comprising: a third speed sensor for detecting RPM of the motor, wherein the controller controls the clutch based on a difference between the RPM of the rear wheel shaft and that of the motor.
- 4. (Original) The four-wheel drive apparatus of claim 3, wherein the motor is controlled in a PWM manner.
- 5. Canceled.
- 6. (Currently Amended) A four-wheel drive method for driving a rear wheel shaft in addition to a front wheel shaft, comprising:

determining if four-wheel drive is required;

generating electric current utilizing a generator connected to an engine;

driving a motor with electric current supplied from the generator; and

driving the rear wheel shaft with a driving force transferred from the motor through a clutch, The four-wheel drive method of claim 5, wherein the determining if four-wheel drive

2

1-SF/7200310.1

is required comprises:

detecting RPM of the front wheel shaft and the rear wheel shaft;

computing a difference between the RPM of the front wheel shaft and that of the rear wheel shaft; and

determining if the computed difference is higher than a predetermined value,

wherein if the difference between the RPM of the front wheel shaft and that of the rear wheel shaft is higher than the predetermined value, four-wheel drive is determined to be required.

7. (Original) The four-wheel drive method of claim 6, wherein the generating of electric current comprises:

computing a torque of the motor required for compensating for the difference between the RPM of the front wheel shaft and that of the rear wheel shaft; and generating electric current based on the required torque.

- 8. (Original) The four-wheel drive method of claim 7, wherein the generating electric current is executed in a feedback control manner.
- 9. (Original) The four-wheel drive method of claim 7, wherein the driving of the motor with electric current supplied from the generator comprises:

detecting RPM of the motor;

applying stator current to a stator of the motor based on the RPM of the motor; and applying rotor current to a rotor of the motor with the generated electric current from the generator.

10. (Original) The four-wheel drive method of claim 9, wherein the driving of the rear wheel shaft with a driving force transferred from the motor comprises:

determining if the RPM of the motor matches the RPM of the rear wheel shaft;

connecting the motor to the rear wheel shaft through the clutch if the RPM of the motor matches the RPM of the rear wheel shaft; and

accelerating the motor if the RPM of the motor does not yet match the RPM of the rear wheel shaft .